## Amendments to the Claims:

The listing of claims will replace all prior versions, and listings, of claims in the application:

## **Listing of Claims**:

Claims 1-10 (Cancelled)

11. (New) A hydraulically driven vehicle, comprising:

a hydraulic pump driven by an engine;

a variable displacement hydraulic motor for traveling driven by pressure oil from the hydraulic pump;

a motor displacement control device that adjusts a displacement of the hydraulic motor in correspondence to a drive pressure at the hydraulic motor;

an operating motor through which a forward travel command and a backward travel command for the vehicle and a command for acceleration and deceleration for the vehicle are issued;

a pilot valve configured to provide a pilot pressure oil in accordance with an extent to which the operating member is operated;

a control valve configured to be driven by the pilot pressure oil from the pilot valve to control a flow of pressure oil from the hydraulic pump to the hydraulic motor;

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a counterbalance valve, that is disposed between the control valve

and the hydraulic motor, configured to be switched to an opening position by the

pressure oil supplied from the hydraulic pump so as to open a return path for oil

to return from the hydraulic motor to the control valve, and to be switched to a

closing position so as to close the return path as the pressure oil from the

hydraulic pump is stopped;

a directional control valve that controls a flow of the pilot pressure

oil which acts on the control valve;

a neutral command device that issues a command for switching the

control valve to a neutral position;

a reverse operation detection device that detects a reverse

operation of the operating member performed to a reverse side opposite from a

direction along which the vehicle is advancing;

a rotation speed detection device that detects a physical quantity

having a correlation to a rotation speed of the hydraulic motor; and

a control device that stops supply of the pressure oil from the

hydraulic pump to the hydraulic motor by interrupting the flow of the pilot

pressure oil to the control valve in response to the command issued from the

neutral command device, regardless of operation of the operating member,

wherein:

when the command is not issued from the neutral command device.

the control device (a) stops supply of the pressure oil from the hydraulic pump to

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the hydraulic motor by interrupting the flow of the pilot pressure oil to the

control valve if the physical quantity detected by the rotation speed detection

device exceeds a reference value and the reverse operation at the operating

member is detected by the reverse operation detection device, and (b) allows the

pilot pressure oil to flow to the control valve, even if the reverse operation at the

operating member is detected, if the physical quantity detected by the rotation

speed detection device is equal to or smaller than the reference value.

12. (New) A hydraulically driven vehicle, comprising:

a hydraulic pump driven by an engine;

a variable displacement hydraulic motor for traveling driven by

pressure oil from the hydraulic pump;

a motor displacement control device that adjusts a displacement of

the hydraulic motor in correspondence to a drive pressure at the hydraulic

motor;

a forward/backward operating member through which a forward

travel command, a backward travel command and a neutral command for the

vehicle are issued;

a traveling operation member through which a command for

acceleration and deceleration for the vehicle is issued in accordance with an

extent to which the traveling operation member is operated;

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a pilot valve configured to provide a pilot pressure oil in response to

an operation of the traveling operation member;

a control valve configured to be driven by the pilot pressure oil from

the pilot valve to control a flow of pressure oil from the hydraulic pump to the

hydraulic motor;

a counterbalance valve, that is disposed between the control valve

and the hydraulic motor, configured to be switched to an opening position by the

pressure oil supplied from the hydraulic pump so as to open a return path for oil

to return from the hydraulic motor to the control valve, and to be switched to a

closing position so as to close the return path as the pressure oil from the

hydraulic pump is stopped;

a directional control valve that controls a flow of the pilot pressure

oil which acts on the control valve in response to an operation of the

forward/backward operating member;

a reverse operation detection device that detects a reverse operation

of the forward/backward operating member performed to a reverse side opposite

from a direction along which the vehicle is advancing;

a rotation speed detection device that detects a physical quantity

having a correlation to a rotation speed of the hydraulic motor; and

a control device that stops supply of the pressure oil from the

hydraulic pump to the hydraulic motor by interrupting the flow of the pilot

pressure oil to the control valve in response to the neutral command issued from

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the forward/backward operating member, regardless of the operation of the

traveling operation member, wherein:

when the neutral command is not issued from the

forward/backward operating member, the control device (a) stops supply of the

pressure oil from the hydraulic pump to the hydraulic motor by interrupting the

flow of the pilot pressure oil to the control valve if the physical quantity detected

by the rotation speed detection device exceeds a reference value and the reverse

operation at the forward/backward operating member is detected by the reverse

operation detection device, and (b) allows the pilot pressure oil to flow to the

control valve, even if the reverse operation at the forward/backward operating

member is detected, if the physical quantity detected by the rotation speed

detection device is equal to or smaller than the reference value.

13. (New) A hydraulically driven vehicle, comprising:

a hydraulic pump driven by an engine;

a variable displacement hydraulic motor for traveling driven by pressure

oil from the hydraulic pump;

a motor displacement control device that adjusts a displacement of the

hydraulic motor in correspondence to a drive pressure at the hydraulic motor;

an operating member through which a forward travel command and a

backward travel command for the vehicle and a command for acceleration and

deceleration for the vehicle are issued;

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a pilot valve configured to provide a pilot pressure oil in accordance with

an extent to which the operating member is operated;

a control valve configured to be driven by the pilot pressure oil from the

pilot valve to control a flow of pressure oil from the hydraulic pump to the

hydraulic motor;

a counterbalance valve, that is disposed between the control valve and the

hydraulic motor, configured to be switched to an opening position by the pressure

oil supplied from the hydraulic pump so as to open a return path for oil to return

from the hydraulic motor to the control valve, and to be switched to a closing

position so as to close the return path as the pressure oil from the hydraulic

pump is stopped;

a first directional control valve that is disposed between the control valve

and the counterbalance valve and controls a flow of the pressure oil from the

hydraulic pump to the hydraulic motor;

a neutral command device that issues a command for switching the control

valve to a neutral position:

a second directional control valve configured to be switched to interrupt

the pilot pressure oil which acts on the control valve in response to the command

issued from the neutral command device, regardless of operation of the operating

member, and configured to be switched to allow the pilot pressure to flow to the

control valve when the command is not issued from the neutral command device;

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a reverse operation detection device that detects a reverse operation of the

operating member performed to a reverse side opposite from a direction along

which the vehicle is advancing;

a rotation speed detection device that detects a physical quantity having a

correlation to a rotation speed of the hydraulic motor; and

a control device that controls the first directional control valve such that

the first directional control valve (a) stops the flow of the pressure oil from the

hydraulic pump to the hydraulic motor when the physical quantity detected by

the rotation speed detection device exceeds a reference value and the reverse

operation at the operating member is detected by the reverse operation detection

device, and (b) allows the pilot pressure oil to flow to the control valve, even if

the reverse operation at the operating member is detected, when the physical

quantity detected by the rotation speed detection device is equal to or smaller

than the reference value.

14. (New) A hydraulically driven vehicle according to claim 11,

wherein:

the physical quantity is a vehicle speed and the reference value is set to a

smaller value as a gear ratio increases.

15. (New) A hydraulically driven vehicle according to claim 11,

further comprising:

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an inertial force detection device that detects an inertial force applied to the vehicle, wherein:

the reference value is set to a smaller value as a greater inertial force is detected.

16. (New) A hydraulically driven vehicle according to claim 15, wherein:

the inertial force detection device detects a grade of a road surface and the reference value is set to a smaller value as the grade becomes steeper.

17. (New) A hydraulically driven vehicle according to claim 15, wherein:

the inertial force detection device detects a vehicle weight, and the reference value is set to a smaller value as the vehicle weight becomes greater.

18. (New) A hydraulically driven vehicle according to claim 12, wherein:

the physical quantity is a vehicle speed and the reference value is set to a smaller value as a gear ratio increases.

19. (New) A hydraulically driven vehicle according to claim 12, further comprising:

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an inertial force detection device that detects an inertial force applied to the vehicle, wherein:

the reference value is set to a smaller value as a greater inertial force is detected.

20. (New) A hydraulically driven vehicle according to claim 19, wherein:

the inertial force detection device detects a grade of a road surface and the reference value is set to a smaller value as the grade becomes steeper.

21. (New) A hydraulically driven vehicle according to claim 19, wherein:

the inertial force detection device detects a vehicle weight, and the reference value is set to a smaller value as the vehicle weight becomes greater.

22. (New) A hydraulically driven vehicle according to claim 13, wherein:

the physical quantity is a vehicle speed and the reference value is set to a smaller value as a gear ratio increases.

23. (New) A hydraulically driven vehicle according to claim 13, further comprising:

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an inertial force detection device that detects an inertial force applied to the vehicle, wherein:

the reference value is set to a smaller value as a greater inertial force is detected.

24. (New) A hydraulically driven vehicle according to claim 23, wherein:

the inertial force detection device detects a grade of a road surface and the reference value is set to a smaller value as the grade becomes steeper.

25. (New) A hydraulically driven vehicle according to claim 23, wherein:

the inertial force detection device detects a vehicle weight, and the reference value is set to a smaller value as the vehicle weight becomes greater.